

6.310

10/16/23

IR

 $\overline{I}$ 

$$\frac{d}{dt} \bar{Y}(t) = Y'(t) = B_Y \bar{W}(t) + \gamma_Y W(t)$$

$$W'(t) = B_W W(t) + \gamma_W R(t)$$

$$R'(t) = B_R R(t) + \gamma_R U(t)$$

known

Assume  $U(t) = \underline{U} e^{st}$

Guess  $Y(t) = \underline{Y} e^{st}$   $W(t) = \underline{W} e^{st}$   $R(t) = \underline{R} e^{st}$

$$\Rightarrow s \underline{Y} e^{st} = B_Y \underline{Y} e^{st} + \gamma_Y \underline{W} e^{st}$$

$$\Rightarrow \underline{Y} = \frac{\gamma_Y}{s + B_Y} \underline{W}$$

$$\begin{aligned} s \underline{W} &= B_W \underline{W} + \gamma_W \underline{R} \Rightarrow \underline{W} = \frac{\gamma_W}{s + B_W} \underline{R} \\ s \underline{R} &= B_R \underline{R} + \gamma_R \underline{U} \quad \underline{R} = \frac{\gamma_R}{s + B_R} \underline{U} \end{aligned}$$

Subbing

$$\underline{Y} = \frac{\gamma_Y}{s + B_Y} \cdot \frac{\gamma_W}{s + B_W} \cdot \frac{\gamma_R \underline{U}}{s + B_R} = \frac{\gamma_Y \gamma_W \gamma_R}{(s + B_Y + B_W + B_R) \underline{U}}$$

N(s) (numerator)

$$(B + B_Y + B_Y B_W + B_W B_R + B_Y B_W B_R)$$

$$\underline{Y} = \left( \frac{\sum_{k=0}^n b_k s^k}{\sum_{k=0}^m a_k s^k} \right) \underline{U}$$

(denom) D(s)

H(s)

ZR

$$D(s) \quad N(s)$$

$$(a_0 s^L + a_1 s^{L-1} + \dots + a_L) I = (b_0 s^L + \dots + b_L) II$$

$$a_0 \frac{d^L y}{dt^L} + \dots + a_L \frac{dy}{dt^L} + a_0 y = b_0 \frac{d^L u(t)}{dt^L} + \dots + b_L \frac{du(t)}{dt^L} + b_0 u(t)$$

If  $I = 0$  then either

$$D(s) = 0 \quad \text{or} \quad I = 0$$

roots of  $D(s)$

natural freqs = roots of  $N(s)$

Natural Response  $\rightarrow y(t) = Y_1 e^{s_1 t} + \dots + Y_L e^{s_L t}$

$$I \quad I = \sum I_i \quad \text{Decays to zero}$$

If  $\operatorname{Re}(s_i) < 0$   
 $\Re(s_i), \Im(s_i)$

Perticular solution If  $U(t) = I e^{s_0 t}$

$\frac{\text{Note}}{\text{Z.S.R}}$ $y_N(t) \neq 0$ even if $y(0) = y'(0) = y''(0) = \dots = y^{(L-1)}(0) = 0$	$y(t) = Y_N(t) + H(s_0) I e^{s_0 t}$ $\downarrow$ used to match initial conditions
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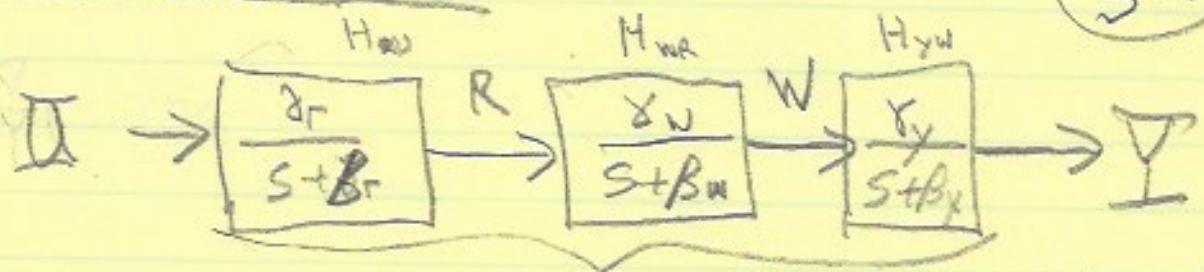
particular solution

$H(s) = \frac{D(s)}{D(s)}$

$\frac{D(s)}{D(s)} \leftarrow$  Roots are zeros of  $N(s)$   
 $\frac{D(s)}{D(s)} \leftarrow$  Roots are poles aka not freqs.

## Block Diagrams

3R

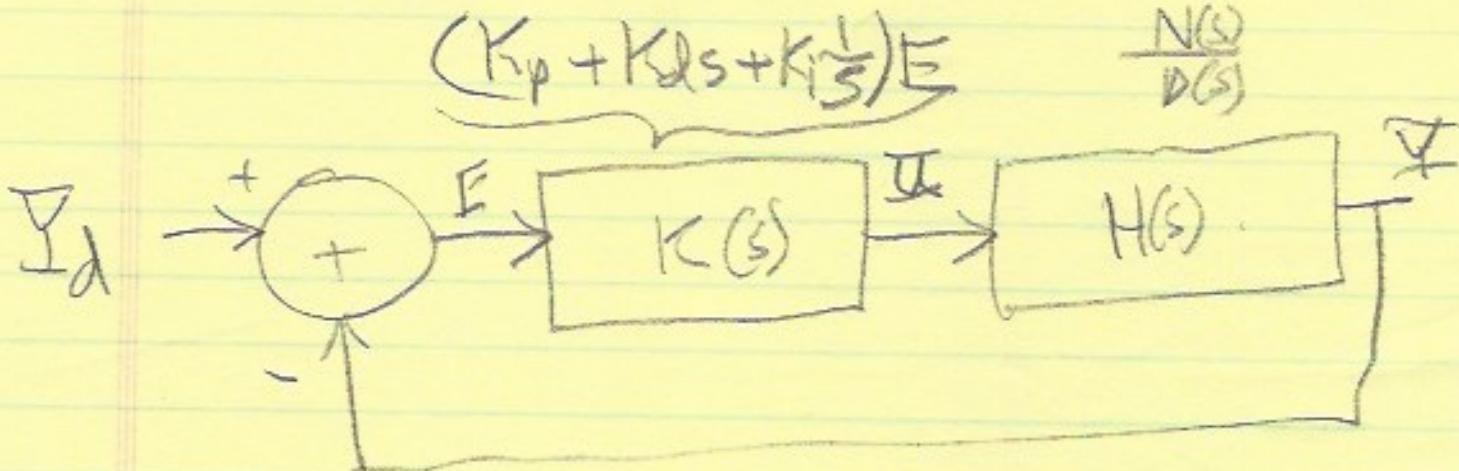


Feedback  $E_{(err)}$



K(s) ?

$$K_p + K_d s + K_i \frac{1}{s}$$



$$Y = H(s) K(s) (I_d - Y)$$

$$(1 + H(s) K(s)) Y = H(s) K(s) I_d$$

Blocks  
Formula

$$Y = \frac{H(s) K(s)}{1 + H(s) K(s)} I_d$$

4 R

Aside on Root Locus

$$Y = \frac{\overset{G(s)}{\overbrace{N(s)}}}{\underset{D(s)}{\underbrace{1 + \frac{N(s)}{D(s)} K(s)}}} U$$

$$= \frac{N(s) K(s)}{D(s) + N(s) K(s)} U$$

$$K(s) = K_0 \left( K_p + K_d s + K_i \frac{1}{s} \right)$$

$$\text{if } K_0 \rightarrow 0$$

poles  $G(s) \rightarrow$  poles of  $D(s)$

$$K_i \rightarrow \infty$$

poles  $G(s) \rightarrow$  roots of  $N(s)$

(5R)

In sinusoidal steady state

$$Y_d(t) = Y_d e^{j\omega t}$$

$$\underline{Y} = \frac{\underline{H}(s) \underline{K}(s)}{1 + \underline{K}(s)\underline{H}(s)} \Big|_{s=j\omega} \underline{Y}_d$$

Assume Re[poles ( $G(s)$ )] < 0       $s = j\omega$

$$Y(t) = G(j\omega) \cdot \underline{Y}_d e^{j\omega t} \quad \text{for } t \text{ large enough}$$

If  $\omega = 0$  (steady state)

$$\lim_{t \rightarrow \infty} Y(t) = Y_{ss} = Y_{ss} = G(j\omega) \Big|_{\omega=0} Y_d(s) = Y_{dss} = \lim_{t \rightarrow \infty} Y_d(t)$$

PID (Assume stability  $\text{Re}(\text{roots } K(s)) < 0$ )

$$\underline{H}(s) = \frac{N(s)}{D(s)} \Rightarrow G(s) = \frac{N(s)(K_p + K_d s + K_i \frac{1}{s})}{D(s) + N(s)(K_p + K_d s + \frac{1}{s})} = \frac{N(s)(K_p s^2 + K_i)}{s D(s) + N(s)(K_p s^2 + K_i)}$$

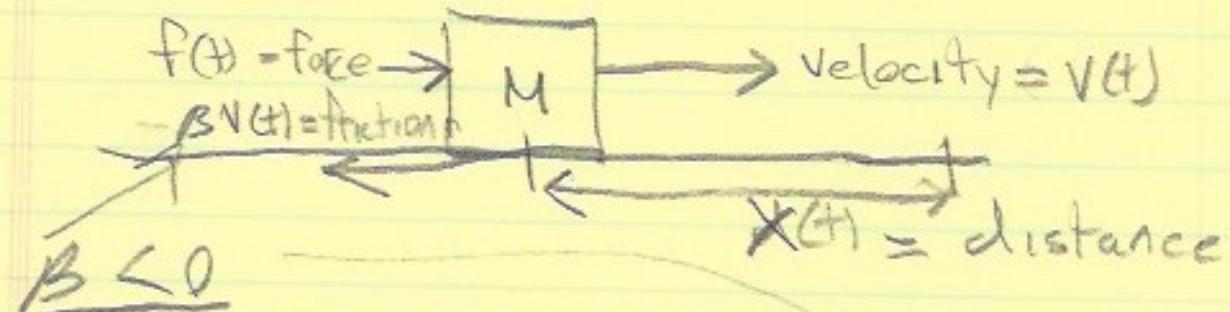
$$K(s) = K_p + K_d s + K_i \frac{1}{s}$$

$$\text{If } K_i > 0 \text{ and } G(s) = 1 \quad \Rightarrow \quad = \frac{N(0) K_i}{N(0) K_i}$$

If  $K_i = 0$

$$G(s) \Big|_{s=0} = \frac{N(0) K_p}{D(0) + N(0) K_p} \Rightarrow 1$$

$\lim_{K_p \rightarrow \infty}$

Example

$$\frac{d}{dt} v(t) = \frac{1}{M} (f(t) + \beta v(t))$$

$$\frac{d}{dt} x(t) = v(t)$$

$$f(t) = k_p (x_d(t) - x(t))$$

Assume  $v(t) = V e^{st}$ , etc

$$s \bar{V} = \frac{1}{M} \bar{F} + \frac{\beta}{M} \bar{V}$$

$$\bar{V} = \frac{1/M}{s - \beta/M} \bar{E}$$

$$s \bar{x} = \bar{V} \quad \bar{x} = \frac{1}{s} \bar{V}$$

$$x(t) = \int v(t) dt$$

$$\bar{x} = \frac{1/M}{s(s - \beta/M)} \bar{F} \quad (\text{in S.S.})$$

$$\bar{F} = k_p (\bar{x}_d - \bar{x})$$

ZL

$$X = \frac{K_p / M / (s^2 - B/M s)}{1 + K_p (Y_H / (s^2 - B/M s))} X_d$$

$$= \frac{K_p / M}{s^2 - (B/M)s + K_p / M} X_d$$

$$= \frac{K_p / M}{s^2 + (|B|/M)s + K_p / M} X_d$$

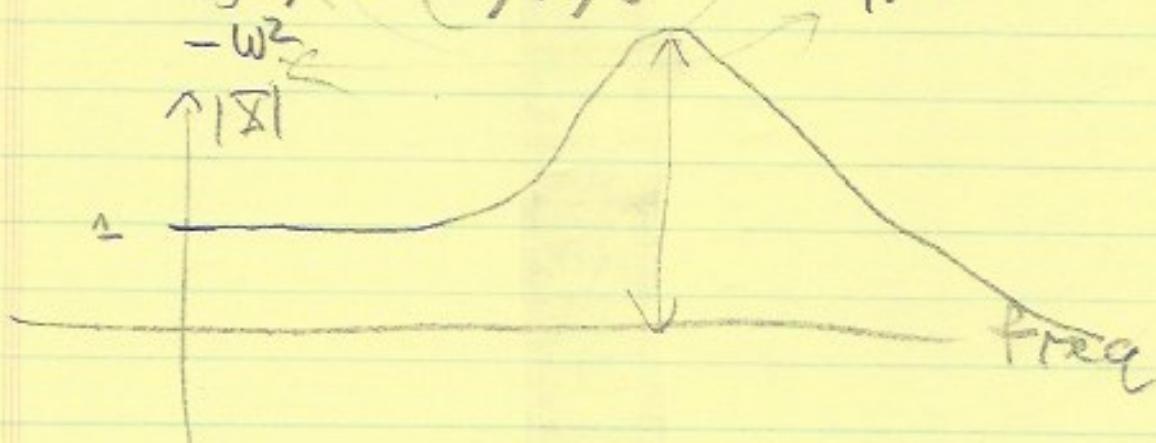
 $B < 0, |B| > 0$ 

Nat freqs

$$\text{Re} \left( \frac{|B|}{M} \pm \sqrt{\frac{|B|^2}{M^2} - 4(K_p Y_H)} \right) < 0$$

Sos. S.

$$X = \frac{K_p / M}{(j\omega)^2 + (|B|/M)j\omega + K_p / M} X_d$$



3L

$$K(s) = K_p + \frac{K_i}{s}$$

$$X = \frac{(K_p + K_i/s)/M}{s^2 + (IB/M)s + (K_p + K_i/s)/M}$$

$$= \frac{s K_p s + K_i / M}{M s^3 + (IB) s^2 + K_p s + K_i} X_d$$

$$\text{If } s = j\omega$$

(4L)

$$K(s) = K_p + K_d s$$

$$\underline{X} = \frac{(K_p + K_d s)}{M s^2 + I B_1 s + (K_p + K_d s)}$$